



Climatix™

Climatix Extension Modules ECV2

POL96U.00/XXX
POL96E.00/XXX

ECV2 extension modules are products of Climatix range. They are designed for driving a broad range of EEV valves with bipolar or unipolar stepper motors. IOs of ECV2 extension modules can be configured for various applications of chiller and heat pump. The extension modules offer the following features:

- Power supply AC 24 V or DC 24 V
- 2 independent channels supporting bipolar ^{*)} stepper motors (chopper drive)
- 12 universal IOs
- DC 24 V and DC 5 V power supplies on board for active sensors
- 4 relay outputs
- 2 Triac outputs: DO1, DO2 (AC 24...230 V)
- 1 digital input galvanically isolated for AC 115/230 V
- Peripheral bus interface for local/remote extension IOs
- LED indicator for stepper motor driver

POL96U.00/XXX has a UPS for driving the electronic valve to a safe position when power failure occurs.

*) unipolar motors in bipolar-current mode only, full step (5, 6, 8-wires)

Electronic expansion valve

Electronic expansion valves control refrigerant mass flow in evaporators in evaporators for chillers, air-conditioners and refrigerators applications. In addition modulating valves can be used for several control functions such as liquid injection, hot gas bypass and evaporator pressure regulation.

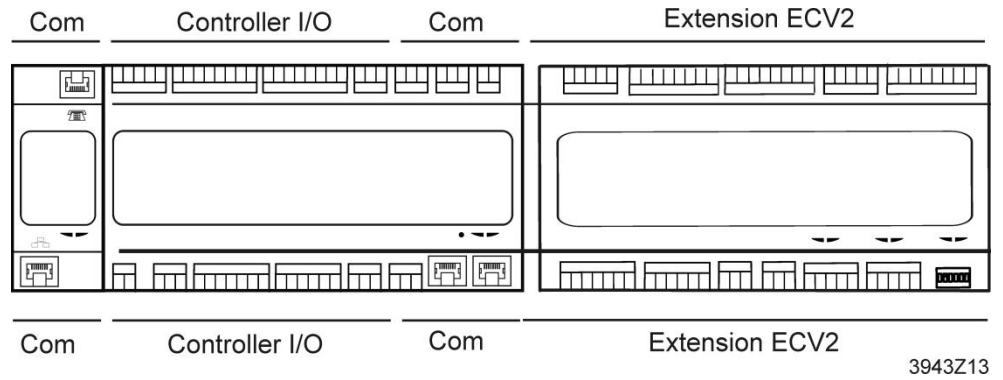
ECV2 extension modules are designed as an electronic expansion valves driver, featuring two independently channel drive bipolar stepper motors. With the main controller one ECV2 module independently can manage two electronic expansion valves. Each channel of ECV2 module controls refrigerant superheat and optimizes the efficiency of the refrigerant circuit, to enhance the maximum capacity for chillers, air-conditioners and refrigerators.

Bipolar stepper motors

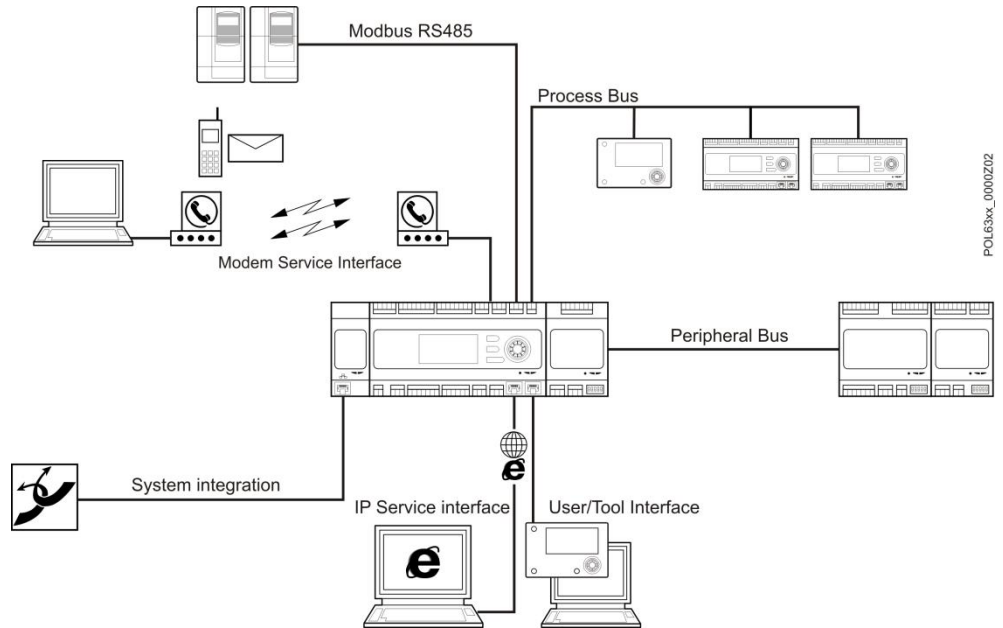
Modulating refrigerant valves that are equipped with bipolar stepper motors are available for a wide capacity range.

Bipolar permanent magnet and hybrid motors have two windings. The drive circuitry for such a motor requires an *H-bridge* control circuit for each winding. Briefly, an H-bridge allows the polarity of the power applied to each end of each winding to be controlled independently.

Installation concept



Communication concept



Disposal

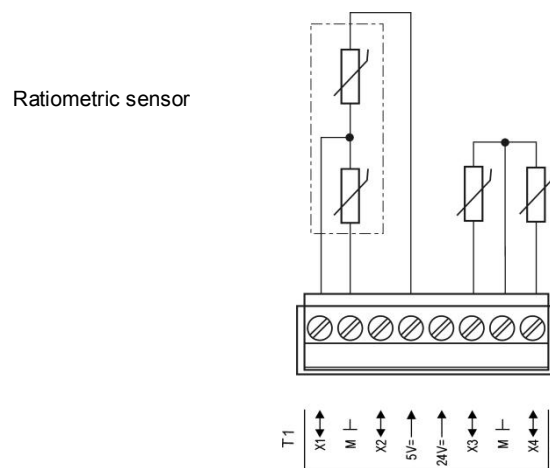


The devices are considered electronics devices for disposal in term of European Directive 2012/19/EU and may not be disposed of as domestic waste.

- Dispose of the device via the channels provided for this purpose.
- Comply with all local and currently applicable laws and regulations.

Technical data

Power supply	Operating voltage	AC 24 V ± 20%; DC 24 V ± 10%
	Frequency	45...65 Hz
	Max. AC-Current consumption	2.2 A, 41 W
	Max. DC-Current consumption	1.9 A, 39 W
	Connection	Peripheral Bus
Power distribution	Max pass through current	3.15A @ AC 24V / 3.54A @ DC 24V
General data	Dimensions in mm	180 x 110 x 75
	Weight excl. packaging	
	POL96U.00/XXX	422.6g
	POL96E.00/XXX	385.5g
	Base	Plastic, pigeon-blue RAL 5014
Housing	Plastic, light-grey RAL 7035	
Universal IOs X1...X12 (T1, T2, T3)	Configurable	By software
	Reference potential	Terminals ⊥
	Contact voltage	Max. DC 24 V (SELV)
	Over voltage protection	Max. 40 V
	Analog inputs (X1...X8)	
Ni1000		
Sensor current	Max. 1.4 mA	
Resolution	0.1 K	
Accuracy in the range -50...150 °C	0.8 K	
Pt1000		
Sensor current	Max. 1.8 mA	
Resolution	0.1 K	
Accuracy in the range -40...120 °C	0.9 K	
0...2.5 kΩ		
Sensor current	Max. 1.8 mA	
Resolution	1 Ω	
Accuracy	5 Ω	
DC 0...5 V input for ratiometric sensors		
Resolution	1 mV	
Accuracy at 0 V	10 mV	
Accuracy at 5 V	30 mV	
Input resistance	100 kΩ	

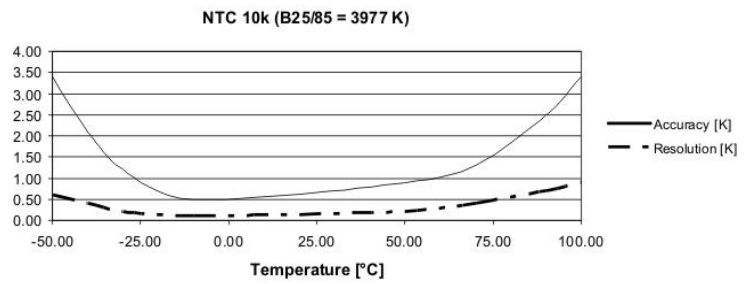
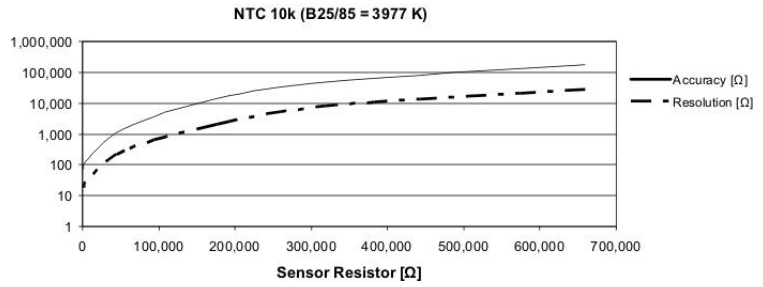


Connecting a ratiometric sensor to universal IOs
Connecting NTC to universal IO

NTC 10k ($B_{25/85} = 3977 \text{ K}$)

Sensor current

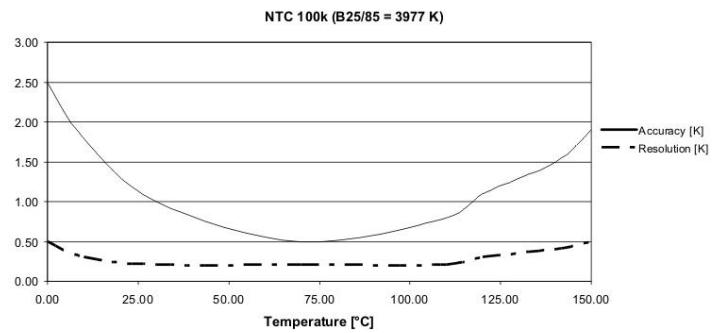
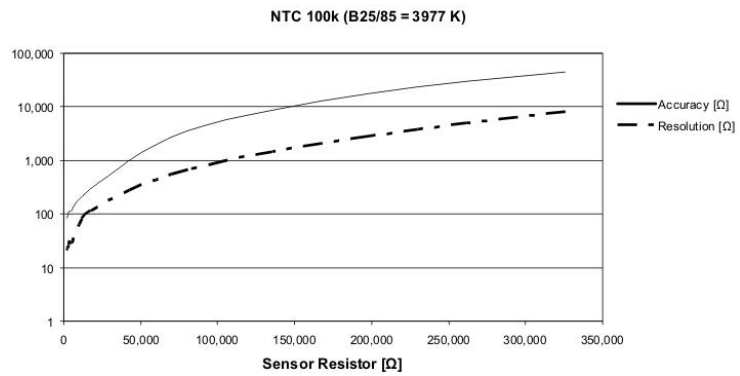
Max. 140 μA



NTC 100k ($B_{25/85} = 3977 \text{ K}$)

Sensor current

Max. 140 μA



Analog inputs (X9...X10)**Ni1000**

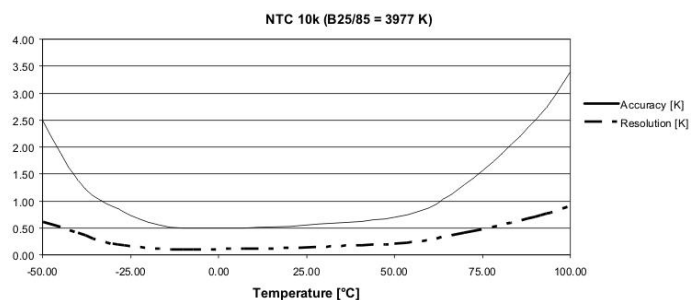
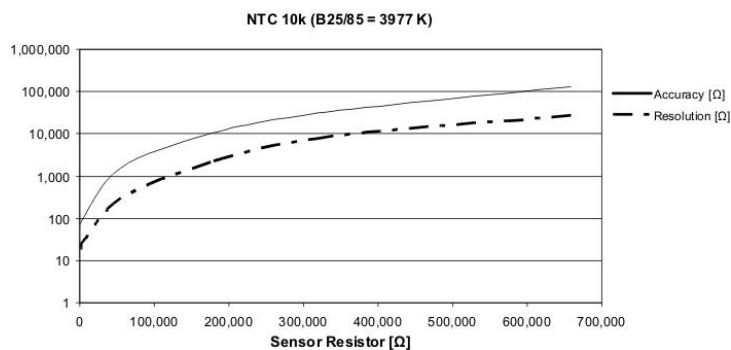
Sensor current	Max. 1.4 mA
Resolution	0.3 K
Accuracy in the range -50...150 °C	0.7 K

Pt1000

Sensor current	Max. 1.8 mA
Resolution	0.3 K
Accuracy in the range -40...120 °C	1.0 K

NTC 10k ($B_{25/85} = 3977 \text{ K}$)

Sensor current	Max. 500 μA
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**Note**

These data are acquired under operating temperature of 25 °C.

Analog inputs (X1...X8)**DC 0...10 V input**

Resolution	1 mV
Accuracy at 0 V	10 mV
Accuracy at 5 V	30 mV
Accuracy at 10 V	50 mV
Input resistance	100 kΩ

DC 0/4...20 mA input

Resolution	1 μA
Accuracy at 4 mA	40 μA
Accuracy at 12 mA	80 μA
Accuracy at 20 mA	120 μA
Impedance of DC 0/4...20 mA	Typ. 450 Ω

Analog inputs (X11...X12)

DC 0...10 V input

Resolution	11 mV
Accuracy at 0 V	45 mV
Accuracy at 5 V	60 mV
Accuracy at 10 V	80 mV
Input resistance	100 kΩ

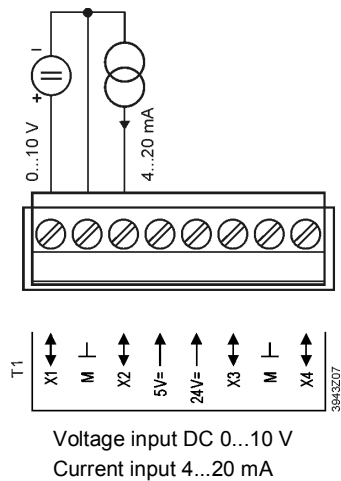
DC 0/4...20 mA input

Resolution	21 μA
Accuracy at 4 mA	85 μA
Accuracy at 12 mA	100 μA
Accuracy at 20 mA	120 μA
Impedance of DC 0/4...20 mA	Typ. 500 Ω

Note



These data are acquired under operating temperature of 25 °C.



Digital inputs (X1...X8)

0/1 digital signal (binary)

Sampling voltage / current

Contact resistance

Delay

Pulse frequency

For potential-free contacts

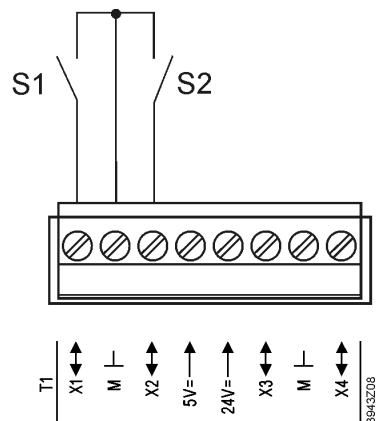
DC 24 V / 8 mA

Max. 200 Ω (closed)

Min. 50 kΩ (open)

10 ms

Max. 20 Hz



Connecting floating contacts to universal IOs

Analog output (X1...X4)

DC 0...10 V output

Resolution	11 mV
Accuracy at 0 V	66 mV
Accuracy at 5 V	95 mV
Accuracy at 10 V	124 mV
Output current	1 mA (short-circuit-proof)

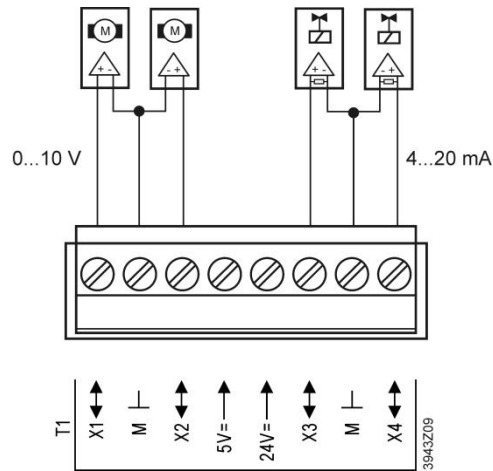
DC 4...20 mA output

Resolution	22 μ A
Accuracy at 4 mA	220 μ A
Accuracy at 12 mA	196 μ A
Accuracy at 20 mA	243 μ A

Note



These data are acquired under operating temperature of 25 °C.



Connecting voltage output and current output to universal IOs

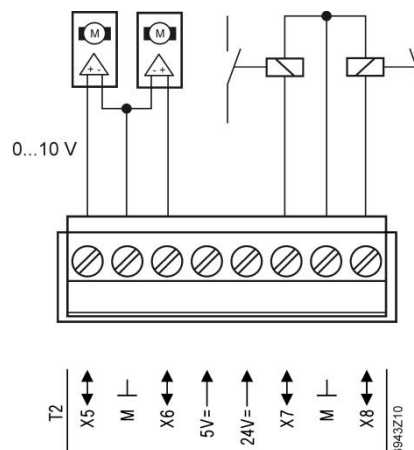
Analog / digital outputs (X5...X8)

DC 0...10 V output

Resolution	11 mV
Accuracy at 0 V	66 mV
Accuracy at 5 V	95 mV
Accuracy at 10 V	124 mV
Output current	1 mA (short-circuit-proof)

DC output for off board loads

Switching voltage	DC 24 V
Switching capacity	Max. 25 mA



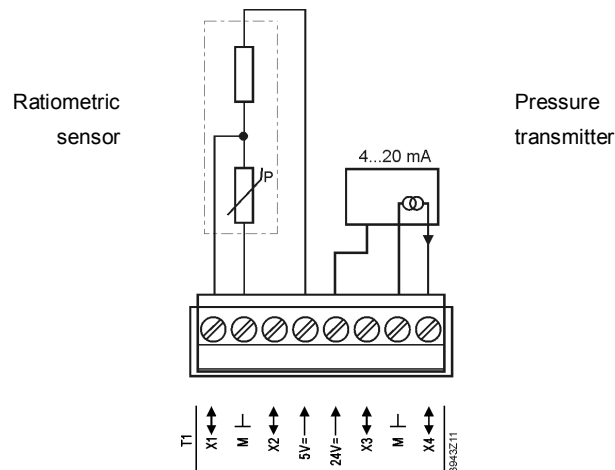
Connecting voltage output and offboard relays to universal IOs

Powering sensors
Active / ratiometric
 5 V, 24 V (T2, T3)

3 x 2 outputs

Voltage / current	DC 5 V: 3x20 mA / $\pm 2.5\%$ ¹⁾
Voltage / current	DC 24 V: 3x40 mA, -25% to +10% accuracy ²⁾
Reference potential	Terminals \perp
Connection	Short-circuit-proof

- ¹⁾ avoid pulsating current
- ²⁾ max. capacitive load 100 μ F



Connecting a ratiometric sensor
 AC 24 V sensor supply voltage

Motor driver
 M1+...COM (T7, T8)

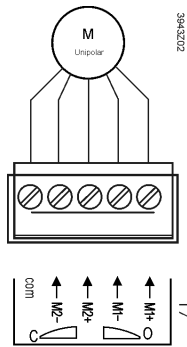
Driver for bipolar stepper motor

Constant-current mode	Short-circuit-proof
Switching frequency	50 kHz (variable)
Full-step mode	4 steps per revolution
Programmable current	0.1...0.5 A ¹⁾
Programmable hold current	0.0...0.5 A
Motor voltage	Max. 42 V
Programmable speed	Max. 500 steps per s
Programmable traverse path	0...30,000 steps
Programmable overdrive	0...2,500 steps
Programmable reference point	Zero or max. point
Max. output power for each motor	10 W
Length of motor cable	<10 m

¹⁾ from VVS11 0.05...0.6 A

UPS (POL96U.00)

Energy storage Ultracaps	(6 x 25 F at 2.21 V)
Usable energy	>187 Ws
Charging time	<3 min



Note



For dedicated valve parameters, approved by valve manufacturers please contact your local Siemens representative.
Examples of approved valves parameters are listed on page 17

Relay outputs
Q1...Q4 (T4)

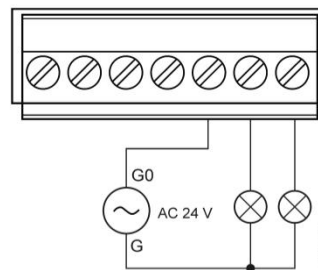
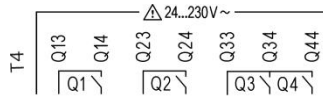
Relay: type, contact	Monostable, NO contact
Contact rating	
Switching voltage	AC 24 V...230 V
Nominal current (res. / ind.)	Max. AC 3 A/2 A (cosφ 0.6)
Switching current at AC 19 V	Min. AC 30 mA



Warning

Do not mix SELV / PELV and line voltage on the same terminal.

Use external protection for inductive load.



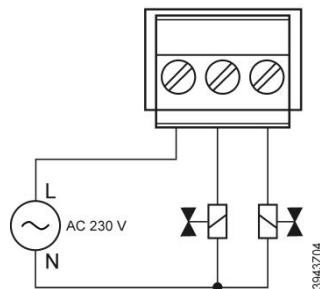
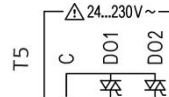
Connecting indicator lamps to relay outputs

Triac outputs
DO1, DO2 (T5)

Triac output values	
Switching voltage	AC 24 V...230 V
Switching capacity	Max. 0.5 A
Min. current	10 mA
Max. external supply line fusing	2.0 A slow wire fuse or circuit breaker

Do not mix SELV / PELV and line voltage on the same terminal.

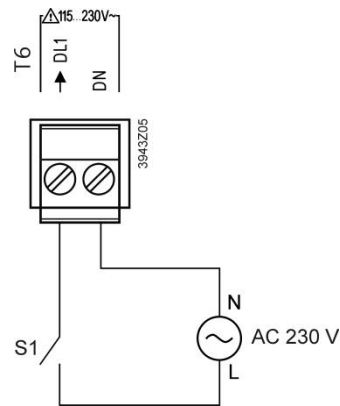
Use external protection for inductive load.



Connecting solenoid valves to Triac output

Digital input AC 230 V
DL1 (T6)

0/1 digital signal (binary)	Galvanically isolated contact
Nominal voltage	AC 115 V...AC 230 V
Frequency range	45...65 Hz
Sample current	3 mA @ AC 230 V
Delay	100 ms
Pulse frequency	Max. 5 Hz



Connecting a AC 230 V signal to a galvanically isolated digital input

Connection terminals

Possible plugs for IO signals (not included)	Phoenix FKCVW 2,5 / x-ST Phoenix FKCT 2,5 / x-ST Phoenix MVSTBW 2,5 / x-ST
Solid wire	0.5...2.5 mm ²
Stranded wire (twisted and with ferrule)	0.5...1.5 mm ²
Cable lengths	In compliance with load, local regulations and installation documents

Peripheral bus

Power supply	U _{eff} = AC 24 V ± 20%, f _{main} = 45...65 Hz or U = DC 24 V ± 10%, no internal fuse
Bus termination	120 Ω +1 nF
Board-to-board (not included)	ZEC 1,0 / 4-LPV-3,5 GY35AUC2C11
Board-to-wire (not included)	ZEC 1,0 / 4-ST-3,5 GY35AUC1R1,4
Stranded wire (twisted and with ferrule)	0.2...1.0 mm ²
Cable lengths	Max. 30 m
Addressing	DIP switches 1...5
Termination	DIP switch 6

Environmental conditions

Operation	3K5 according IEC 721-3-3
Temperature	-40...70 °C (POL96E.00) -40...60 °C (POL96U.00)
Relative humidity	5%...95% (non-condensing)
Absolute humidity	1...29 g/m ³
Atmospheric pressure	Min. 700 hPa, corresponding to Max. 3,000 m above sea level
Transport	IEC 60721-3-2
Temperature	-40...70 °C
Humidity	<95% r.h. (non-condensing)
Atmospheric pressure	Min. 260 hPa, corresponding to Max. 10,000 m above sea level

Protection	Degree of protection	IP20 (EN 60529)
	Pollution degree	2
	Safety class	Suitable for use in plants with safety class II
Standards	EU Conformity (CE)	CB1T3434xx *)
	RCM Conformity	CB1T3434en_C1 *)
	Listings	UL916, UL873 CSA C22.2M205

*) The documents can be downloaded from <http://siemens.com/bt/download>.

BSP LEDs

The status of the BSP LED is defined as below:

Mode	LED
BSP upgrade mode in progress	Per second flashing between red and green.
Application not loaded	Orange flashing with 50ms on and 1000ms off
Application loaded but not running or BSP Upgrade mode active	Orange
Application running	Green
BSP error (software error)	Red flashing with 2Hz
Hardware error	Red
Fail safe mode (in case that the BSP upgrade was interrupted)	Orange with Red flashing every second for 500ms

BUS LEDs

This LED indicates the status of the communication with the controller.

Mode	LED
Communication running but parameter from the application wrong or missing, or the calibration from the factory not correct	Orange
Communication running, IO working	Green
Communication down	Red

Note



POL96X.00/XXX is a programmable extension module (for programming instruction of local application see Sapro Online-Help).

In case that a failsafe drive is performed (driver connected and referenced), all outputs and LEDs are switched off during the fail safe drive! If the position is reached and the internal super capacitor has still power, the internal application starts again and can control the outputs (therefore BSP LED green).

ECV closing and opening LEDs

In addition to the standard LED, the stepper has two LEDs for each motor which show the status of the motor.

Status	Open LED	Close LED
Motor not moving in this direction	OFF	OFF
Valve is moving to the fail safe position in case of power fail (only for UPS versions)	OFF	OFF
Motor full open if referenced	ON	OFF
Valve is closing	OFF	Green flashing 250 ms ON 250 ms Off
Valve is opening	Green flashing 250 ms ON / 250 ms OFF	OFF
Valve is moving to the fail safe position closed	OFF	Green short flashing 50 ms ON / 450 ms OFF
Valve is moving to the fail safe position open	Green short flashing 50 ms ON / 450 ms OFF	OFF
Stepper error (for example, the diagnostics detected an error at startup, such as not connected or shortened coil)	Green short flashing 50 ms ON // 450 ms OFF	Green short flashing 50 ms ON / 450 ms OFF

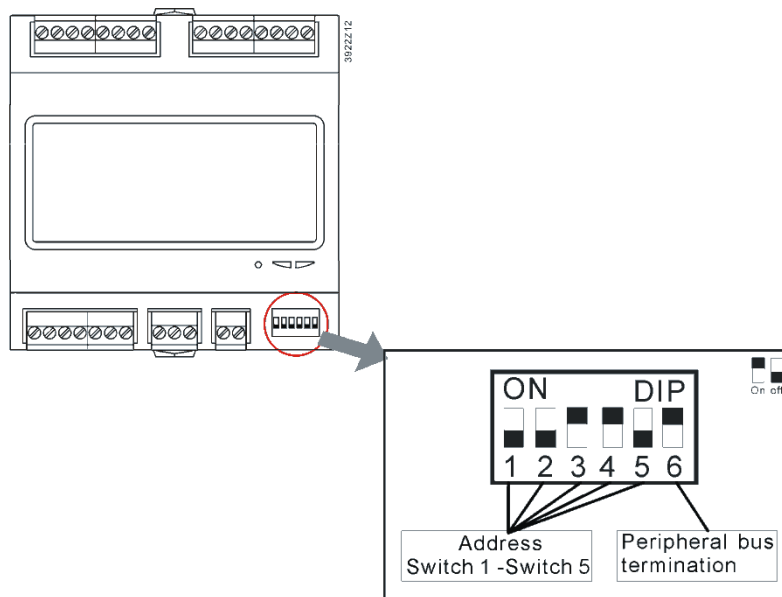
Note



Firmware of POL96X.00/XXX features different diagnostic functions such as disconnection detection, under voltage detection or shorted coil. The function "disconnection detection" is active only during valve / motor positioning, but not during hold on.

DIP switches

The extension module is equipped with DIP switches for communication with the controller. Switches 1, 2, 3, 4, and 5 are configurable to set the slave address, while switch 6 acts as peripheral bus termination. When the extension module operates as the termination in the network, switch 6 must be set to ON.



The order of bits for the switch is from 5 to 1, 5 is the lowest bit while 1 is the highest bit. The following table shows the logic of slave address:

Switch 1	2^4
Switch 2	2^3
Switch 3	2^2
Switch 4	2^1
Switch 5	2^0

By combining switches 1, 2, 3, 4 or 5, maximum 31 slave addresses can be configured. The configuration formula is as follows: $2^4+2^3+2^2+2^1+2^0=31$. Below are some configuration examples:

DIP Switch configuration of Extension Module							
No.	Schematics	No.	Schematics	No.	Switch 5	No.	Schematics
1		9		17		25	
2		10		18		26	
3		11		19		27	
4		12		20		28	
5		13		21		29	
6		14		22		30	
7		15		23		31	
8		16		24			

Note



The same address of extension module must be set in the application program of the controller. Zero cannot be set as the slave address.

Order data

Extension module 21 IOs	POL96E.00/STD POL96U.00/STD
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Accessory parts

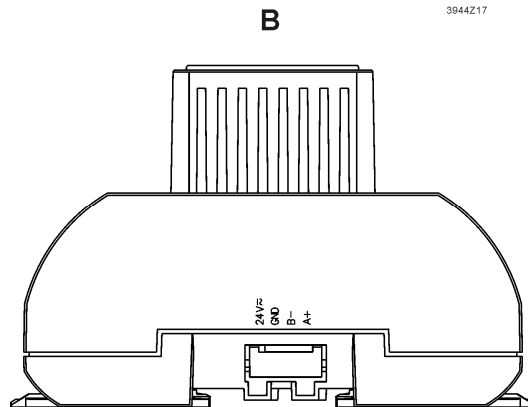
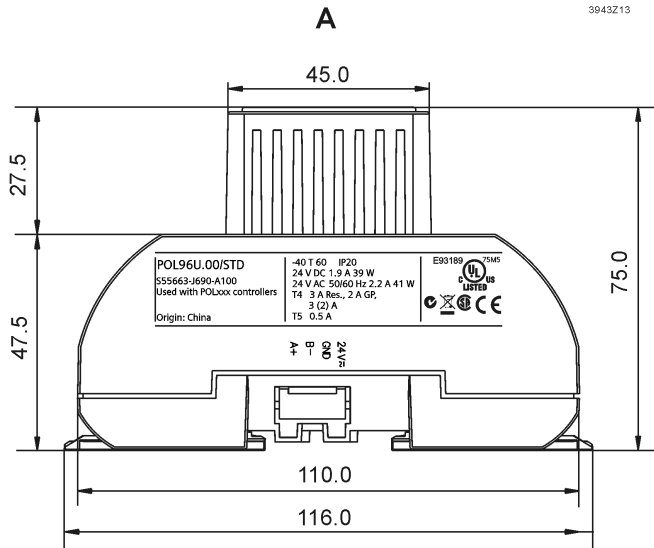
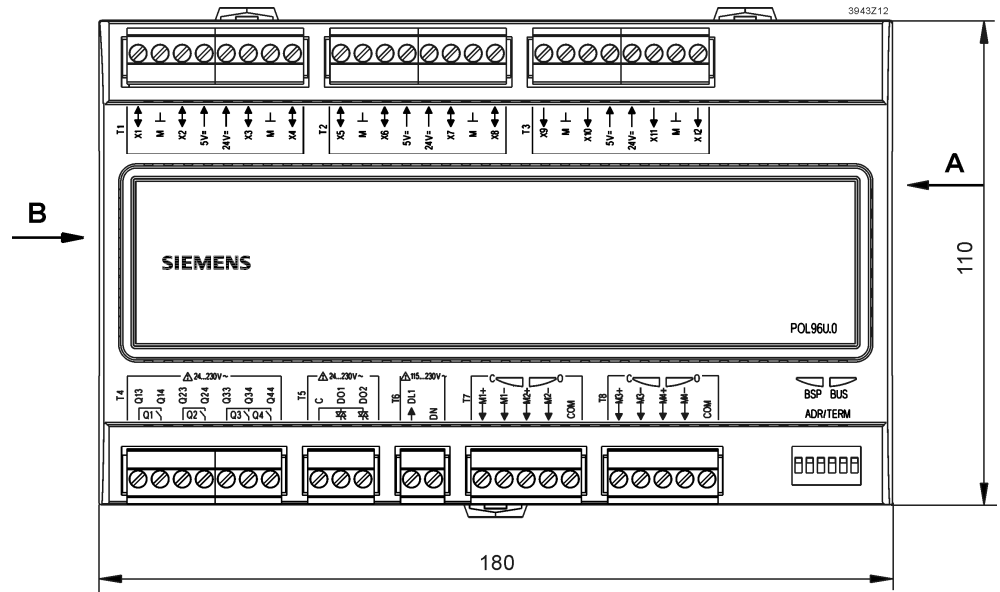
Plug set (screw type, side entry)	POL096.E5/STD
1 x Phoenix MVSTBW 2,5/2-ST GY7035	
1 x Phoenix MVSTBW 2,5/3-ST KMGY	
2 x Phoenix MVSTBW 2,5/5-ST GY7035	
1 x Phoenix MVSTBW 2,5/7-ST GY7035	
3 x Phoenix MVSTBW 2,5/8-ST GY7035	
1 x Phoenix ZEC 1,0/4-LPV-3,5 GY35AUC2C11	
Plug set (spring cage, cable top entry) FKCT	POL096.E6/STD
Board-to-wire connector	POL002.43/STD
2 x Phoenix ZEC 1,0 / 4-ST-3,5 GY35AUC1R1,4	50 pcs

Engineering notes**Warning**

To ensure protection against accidental contact with relay connections carrying voltages above 42 V_{eff}, the module must be installed in an enclosure (preferably a control panel). It must be impossible to open the enclosure without the aid of a key or tool.

AC 230 V cables must be double-insulated against safety extra low-voltage (SELV) cables.

Dimensions (mm)



Valve settings

Manufacturer	Unit / Dimension	Danfoss
Valve Type		ETS 12.5, 25, 50, 100, 250, 400 *
CurrentSetpoint	[mA]	120
Speed	[Steps/s]	300
OverdriveOpen	[Steps]	0
OverdriveClose	[Steps]	300
HoldCurrentSetpoint	[mA]	0
DeadTimeSync	[Min.]	60
DelayDirection	[ms]	200
Step Mode		Full Step
* (SKUs 034G0000-034G4999) Maximum cable length 8 m. If a longer cable length is used, communication inductors such as the Danfoss AKA211 should be used.		

Manufacturer	Unit / Dimension	Sporlan		
Valve Type		SER AA, A, B, C, D	SERI F, G, J, K, L	SEHI P, 175, 400, T
CurrentSetpoint	[mA]	120	140	160
Speed	[Steps/s]	200, 400	240	200, 400
DelayDirection	[ms]	200		
OverdriveOpen	[Steps]	0		
OverdriveClose	[Steps]	300		
HoldCurrentSetpoint	[mA]	0		
DeadTimeSync	[Min.]	480		
TraversePath	[Steps]	2500	2500	6386
Step Mode		Full Step		
Sporlan EEVs are designed for long life and durability. Reinitializing the EEV (overdriving to zero position) more than three times per day is not needed.				

Published by:
Siemens Switzerland Ltd.
Building Technologies Division
International Headquarters
Gubelstrasse 22
6301 Zug
Switzerland
Tel. +41 41-724 24 24
www.siemens.com/buildingtechnologies

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